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> SFERA-III 2nd Summer School October, 5th- 6th, 2021 Almería (Spain)

#### Lecture: Advanced control of solar process heat applications

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#### Automatic control: a (very) brief introduction

 Control structures of continuous systems. SHIP and water desalination processes.



- Device or process working by itself with little or no direct human control.
- To maintain the variables of a process within defined limits, with a desired behavior and minimizing the effect of external variables



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- To maintain the variables of a process within defined limits, with a desired behavior and minimizing the effect of external variables



WHEN YOU'RE IN SOMEONE ELSE'S SHOWER AND YOU GET THE CONTROLS ALL WRONG

#### What do you do during the shower time?

- 1. Open the water tap
- 2. Touch the water with your hand
- 3. Manipulate the tap trying to reach the desired water temperature



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@instachaaz

- 1. To observe the behavior of the real process
- 2. Compare the behavior with the desired one
- 3. Act over the process to reach the desired objective



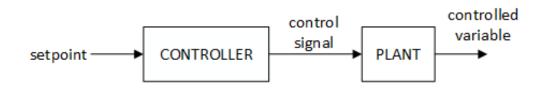
#### Control systems. Some definitions

- **Plant/Process**. The mechanism, device or process to be controlled.
- **Output** (controlled variable, process variable). Variable or property of the plant that must be controlled.
- Input (control variable). Variable or signal that, when adjusted, produces important changes in the plant output
- **Reference** (setpoint). Signal that represents the behavior that is desired at the plant output.
- Error. Difference between the setpoint and the controlled variable
- **Disturbance**. A signal that is external to the control system having deleterious effects on the performance of the closed-loop system.
- Actuator. A device that applies the input signal to the plant.
- **Constraints**. Limitations in the variables



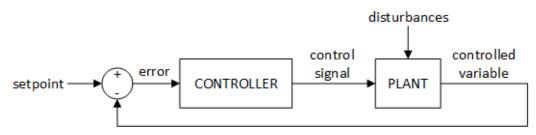
Control systems. Some definitions

 Open-loop control. Information is not gained directly from the measurement of the controlled signal.





• Closed-loop (feedback control). The controlled signal is measured. The control error influences the input of the process





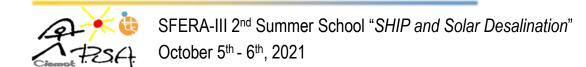
Key concepts



Block diagram



SHIP & solar desalination application



#### **Category I: Basic control approaches**

- PID
- Feedforward
- Cascade controller

#### Category II, III & IV: advanced control

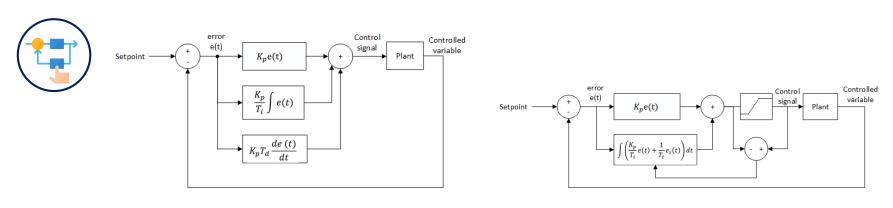
- Gain scheduling GS
- Time delay compensation TDC
- Decoupling control
- Model predictive control MPC
- Neural Network

Seborg, D. E. (1999). A perspective on advanced strategies for process control (revisited). In Advances in Control (pp. 103-134). Springer, London.



#### The PID controller

- The most common algorithm
- · It has the ability of eliminating steady state offsets
- It can anticipate the future

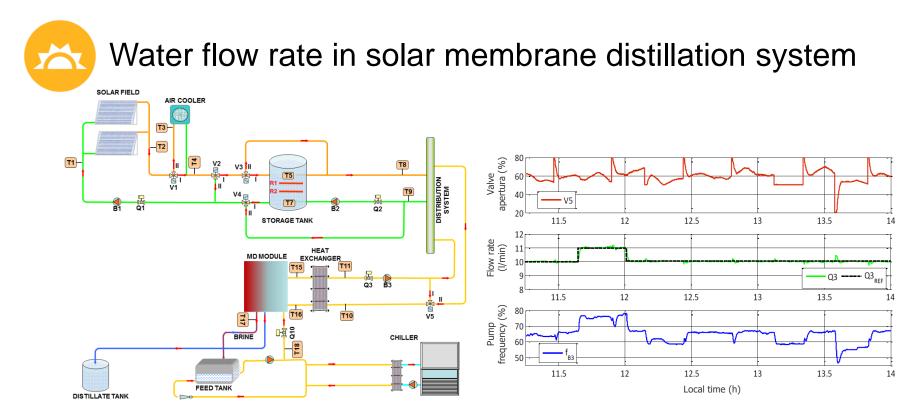


#### **PID Non-interacting form**

Anti-windup



#### The PID controller



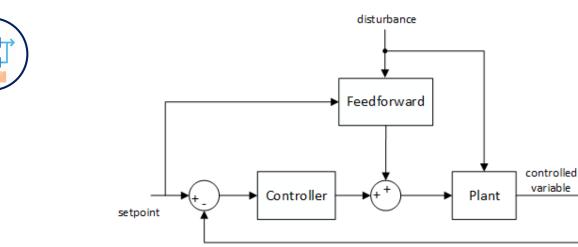
J.D. Gil, A. Ruiz-Aguirre, L. Roca, G. Zaragoza, M. Berenguel, Solar membrane distillation : a control perspective, in: 23rd Mediterr. Conf. Control Autom., 2015: pp. 836–842.



#### The feedforward controller

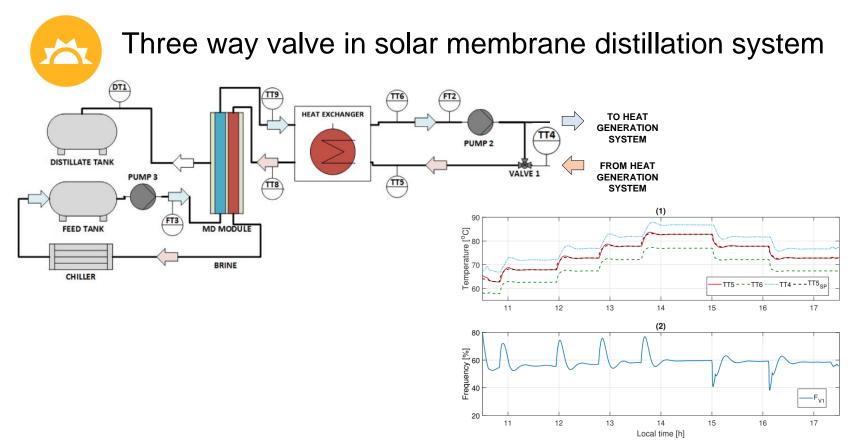


- It eliminates the effect of disturbances before they have created control errors.
- It requires process models
- It requires disturbance measurements
- It complements feedback control





#### The feedforward controller



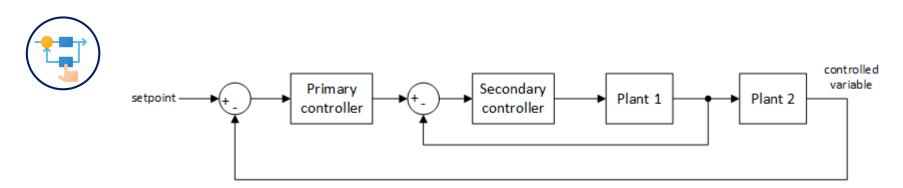
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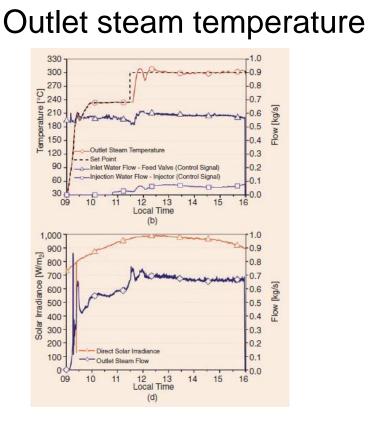
#### Cascade controller

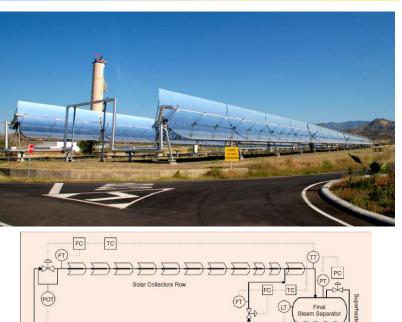
- It can be used when there are several measurement signals and one control variable.
- It splits the control problem in two time scales and two control loops: an inner control loop (slave) and the outer control loop (master).

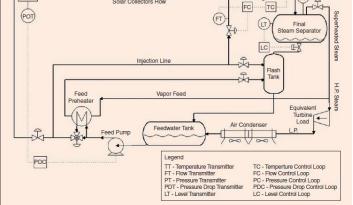




#### Cascade controller







L. Valenzuela, E. Zarza, M. Berenguel, E.F. Camacho, Direct steam generation in solar boilers, IEEE Control Syst. Mag. 24 (2004) 15–29.



#### **Category I: Basic control approaches**

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#### Category II, III & IV: advanced control

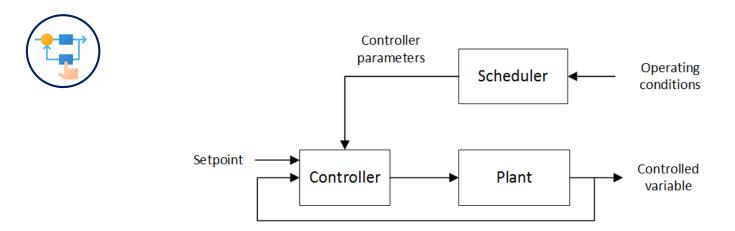
- Gain scheduling GS
- Time delay compensation TDC
- Decoupling control
- Model predictive control MPC
- Neural Network

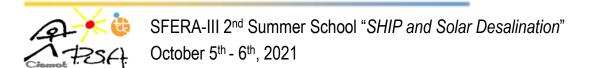
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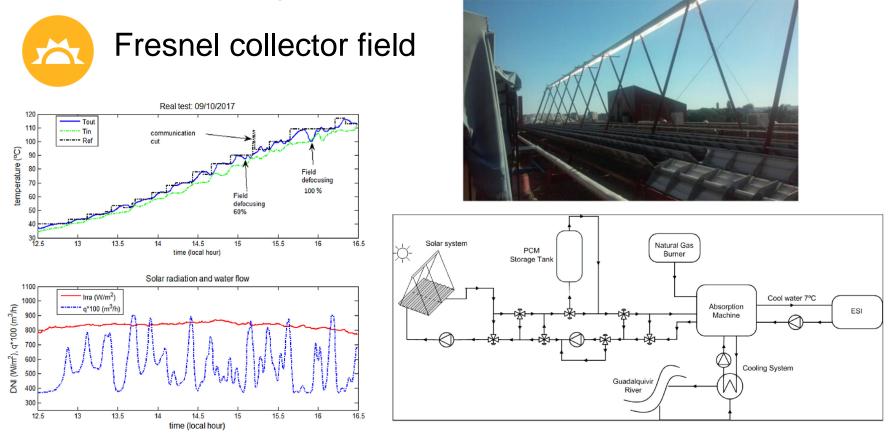
#### Gain scheduling

- Controllers that have the ability of adapting to changes in process dynamics
- Controller parameters can be computed from measurement variables related to the operating point or operating conditions





#### Gain scheduling



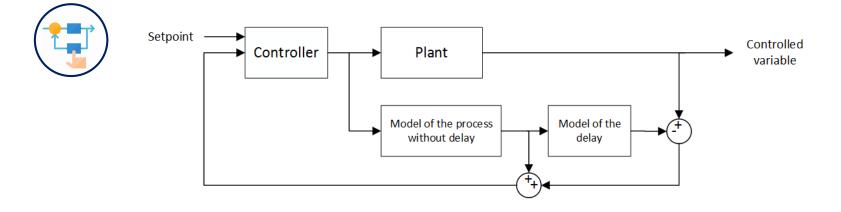
Gallego, A. J., Merello, G. M., Berenguel, M., & Camacho, E. F. (2019). Gain-scheduling model predictive control of a Fresnel collector field. Control Engineering Practice, 82, 1-13.



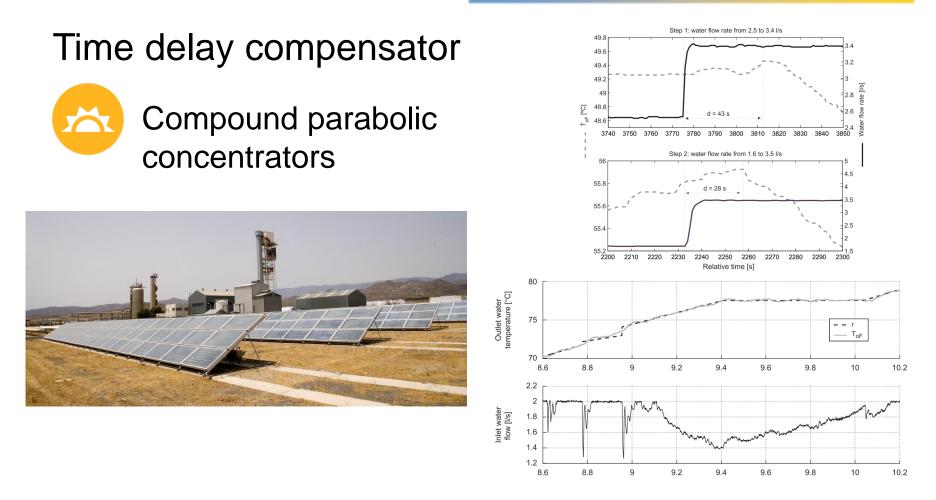
#### Time delay compensation



- Dead times appears in many solar processes, usually associated with mass transport or doe to the accumulation of several low-order systems.
- In TDC schemes, the controller is designed without considering the delay of the process







L. Roca, J.L. Guzman, J.E. Normey-Rico, M. Berenguel, L.J. Yebra, Robust constrained predictive feedback linearization controller in a solar desalination plant collector field, Control Eng. Pract. 17 (2009) 1076–1088. L. Roca, J.L. Guzman, J.E. Normey-rico, M. Berenguel, Filtered Smith Predictor with nonlinear model applied to a solar field, in: 2014 Eur. Control Conf., Strasbourg, France, 2014.



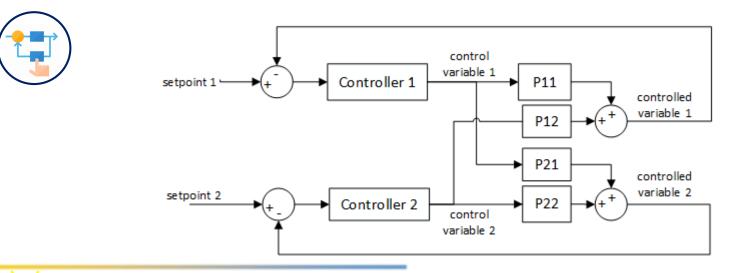
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#### **Decoupling control**



- In Multi-Input-Multi-Output (MIMO) systems we must control simultaneously M variables with N available control signals.
- One of the most important problems in MIMO systems control is the coupling problem
- We can use decouplers to compensate for undesirable process
  interactions



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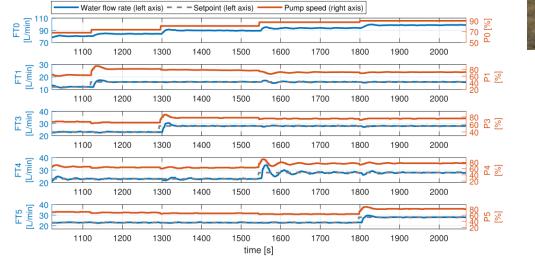
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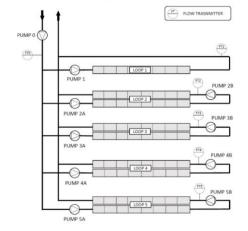
#### **Decoupling control**



#### Flat plate collectors







A. Tosi, L. Roca, J.D. Gil, A. Visioli, M. Berenguel, Multivariable controller for stationary flat plate solar collectors, in: Proc. 7th Int. Conf. Syst. Control, Valencia (Spain), 2018; pp. 7–12.



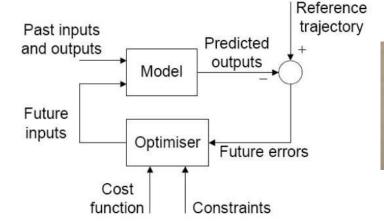
#### Model predictive control

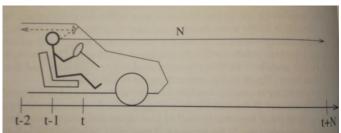


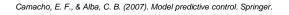
It does not designate a specific control strategy but an ample range of control methods. The ideas are:

- Explicit use of a model to predict the process output at future time (horizon)
- The control sequence is calculated by minimizing an objective function
- Receding strategy

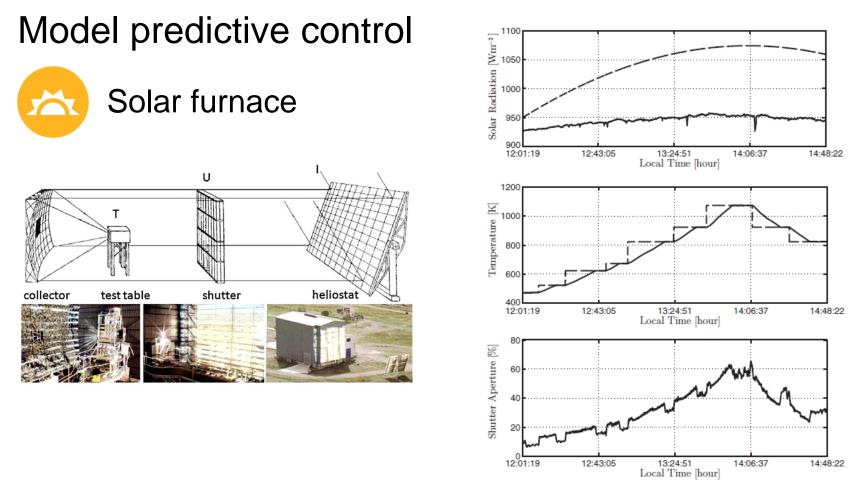












Beschi, M., Berenguel, M., Visioli, A., Guzmán, J. L., & Yebra, L. J. (2013). Implementation of feedback linearization GPC control for a solar furnace. Journal of Process Control, 23(10), 1545-1554



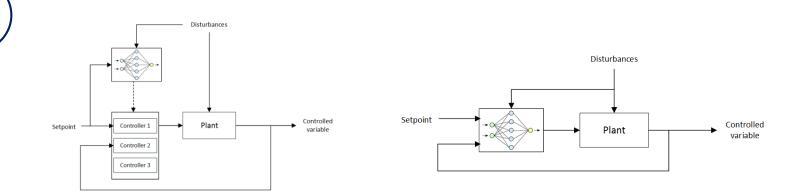
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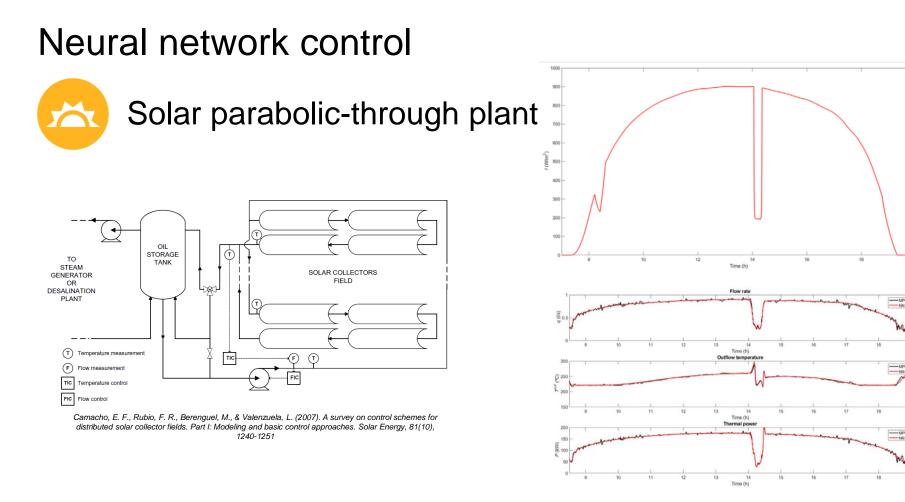
#### Neural network control



- Artificial Neural Networks (ANN) are models designed to emulate the human brain
- They are good for tasks to complete information, they can learn from examples and are able to deal with non-linear problems.
- They can be used in diverse applications in control (to model the behavior of the plant or to calculate the control signal)







Ruiz-Moreno, S., Frejo, J. R. D., & Camacho, E. F. (2021). Model predictive control based on deep learning for solar parabolic-trough plants. Renewable Energy, 180, 193-202

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# **End of Presentation**

- Thank you for your attention
- Questions ?

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